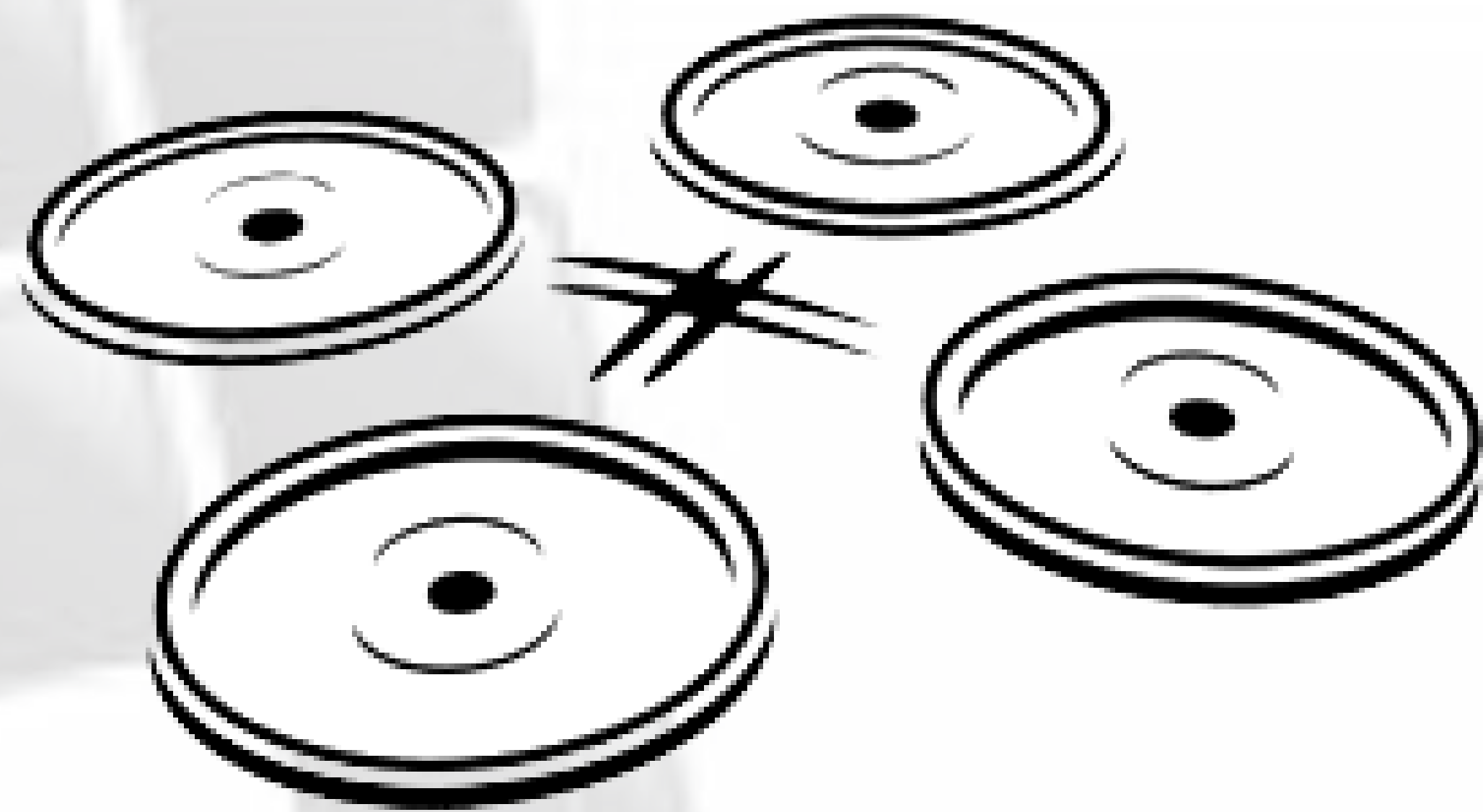


# PROJECT OVERLORD

**Project Overlord** aims to develop a mobile, stable and versatile platform to provide real time telemetry to a portable ground station wirelessly

the **P**latform



SPECS:

Z510 intel atom

1 Gb ram

12x3.8 props

Turnigy 18 Amp motors

Turnigy plush 30 Amp esc

Mikrocopter frame

Life A123 battery

the **C**onnection



Wireless N

the **U**ses

Firefighting

Inspecting infrastructure

Photogrammetry

Autonomous surveillance

the **G**round **S**tation

*QGroundControl*

Open Source MAV Ground Control Station

Any computer with wi-fi